

RI360P0-EQR24M0-IOLX2-H1141 Contactless Encoder with Stainless Steel Housing – IO-Link Premium Line





Technical data

Туре	RI360P0-EQR24M0-IOLX2-H1141
ID	1590978
Measuring principle	Inductive
General data	
Max. rotational speed	800 rpm
	Determined with standardized construction, with a steel shaft $Ø$ 20 mm, L = 50 mm and reducer $Ø$ 20 mm.
Starting torque shaft load (radial / axial)	not applicable, because of contactless measuring principle
Measuring range	0360 °
Nominal distance	1.5 mm
Repeat accuracy	≤ 0.01 % of full scale
Linearity deviation	≤ 0.05 % f.s.
Temperature drift	≤ ± 0.003 %/K
Output type	Absolute semi-multiturn
Resolution singleturn	16 bit/65,536 units per revolution
Resolution multiturn	13 bit/8192 revolutions
Number of diagnostic bits	3 Bit
Electrical data	
Operating voltage U _B	1530 VDC
	≤ 10 % U _{вмах}
Isolation test voltage	0.5 kV
Wire break/reverse polarity protection	yes (voltage supply)

Features

- Compact, rugged housing
- Active face, plastic PA12-GF30
- Housing, stainless steel V4A (1.4404)
- Status displayed via LED
- Immune to electromagnetic interference
- 16 bits singleturn
- Process value in 32 bit IO-Link telegram
- 3 error bits
- 16 bits singleturn
- 13 bits multiturn
- 15...30 VDC
- M12 × 1 male connector, 4-pin

Wiring diagram





Functional principle

The measuring principle of inductive encoders is based on oscillation circuit coupling



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Communication protocol	IO-Link
Sample rate	1000 Hz
Current consumption	< 50 mA
IO-Link	
IO-Link specification	V 1.1
Programming	FDT/DTM
Communication mode	COM 2 (38.4 kBaud)
Process data width	32 bit
Minimum cycle time	3 ms
Function pin 4	IO-Link
Included in the SIDI GSDML	Yes
Mechanical data	
Design	EQR24
Dimensions	81 x 78 x 24 mm
Flange type	Flange without mounting element
Shaft Type	Hollow shaft
	6.35 9.525 10 12 12.7 14 15.875 19.05 20
Housing material	Stainless-steel/Plastic, 1.4404 (AISI 316L)/ PA12-GF30
Electrical connection	Connector
Environmental conditions	
Ambient temperature	-25+85 °C
	Acc. to UL approval to +70 °C
Vibration resistance	55 Hz (1 mm)
Vibration resistance (EN 60068-2-6)	20 g; 103000 Hz; 50 cycles; 3 axes
Shock resistance (EN 60068-2-27)	100 g; 11 ms ½ sine; 3 × each; 3 axes
Continuous shock resistance (EN 60068-2-29)	40 g; 6 ms ½ sine; 4000 × each; 3 axes
Protection class	IP68 IP69K
MTTF	138 years acc. to SN 29500 (Ed. 99) 40 °C
Power-on indication	LED, Green
Measuring range display	LED, yellow, yellow flashing

between the positioning element and the sensor, whereby an output signal is provided proportional to the angle of the positioning element. Turck refers to semi-multiturn because the multiturn process data is calculated internally from the number of single-turn zero passes. Because the sensor does not detect any revolutions when not supplied with power, the plausibility of the multiturn process data is indicated by a diagnostic bit. The rugged sensors are maintenanceand wear-free thanks to the contactless operating principle. They convince through their excellent repeatability, resolution and linearity within a broad temperature range. The innovative technology ensures high immunity to electromagnetic DC and AC fields.



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Included in delivery

Adapter sleeve MT-QR24

UL certificate

E210608



Mounting instructions



Extensive range of mounting accessories for easy adaptation to many different shaft diameters. Based on the functional principle of RLC coupling, the sensor operates absolutely wear-free and is immune to magnetized metal splinters and other interference fields. Wrong installation is hardly possible.

The adjacent figure shows the two separate units, sensor and positioning element. Mounting option A:

First, interconnect positioning element and rotatable shaft. Then place the encoder above the rotating part in such a way that you get a tight and protected unit.

Mounting option B: Push the encoder on the back site of the shaft and fasten it to the machine. Then clamp the positioning element to the shaft with the bracket.

Mounting option C:

If the positioning element is to be screwed on a rotating machine part and not on a shaft, install first the dummy plug RA8-QR24. Then tie up the bracket. Screw on the encoder via the three bores.

The separately arranged sensor and positioning element inhibit that compensating currents or damaging mechanical loads are transmitted via the shaft to the sensor. In addition, the encoder remains tight and highly protected during its entire lifespan.

The accessories enclosed in the delivery help to mount encoder and positioning element at an optimal distance from each other. LEDs indicate the switching status. Optionally, you can use the shields which are included in the accessories to increase the allowed distance between positioning element and sensor.

Status display via LED green steady: Sensor is operative yellow steady: Positioning element has reached the end of the measuring range. This is indicated by a weaker signal. vellow flashing: Positioning element is outside the measuring range. off:

Positioning element is in the measuring range



Accessories







Wiring accessories

