

RI360P0-QR24M0-HESG25X3-H1181 Contactless Encoder – SSI Premium Line





Technical data

Туре	RI360P0-QR24M0-HESG25X3-H1181
ID	1590905
Measuring principle	Inductive
General data	
Max. rotational speed	6000 rpm
	Determined with standardized construction, with a steel shaft Ø 20 mm, L = 50 mm and reducer Ø 20 mm
Starting torque shaft load (radial / axial)	not applicable, because of contactless measuring principle
Measuring range	0360 °
Nominal distance	1.5 mm
Repeat accuracy	≤ 0.01 % of full scale
Linearity deviation	≤ 0.05 % f.s.
Temperature drift	≤ ± 0.003 %/K
Output type	Absolute semi-multiturn
Resolution singleturn	16 bit/65,536 units per revolution
Resolution multiturn	6 bit/64 revolutions
Number of diagnostic bits	3 Bit
Electrical data	
Operating voltage $U_{\scriptscriptstyle B}$	1530 VDC
Ripple U _{ss}	≤ 10 % U _{Bmax}
Isolation test voltage	0.5 kV
Wire break/reverse polarity protection	yes (voltage supply)

Features

Compact, rugged housing
Many mounting possibilities
Status displayed via LED
Positioning element and aluminium ring not
incl.
SSI output
25 bit, Gray-coded
SSI clock rate: 62.5 KHz 1 MHz
Single or multiturn, length of data frame and
bit coding parametrizable via PACTware
with programming box USB-2-IOL-0002 and
adapter cable RKC8.302T-1,5-RSC4T/TX32
Default settings: Singleturn Bit 0 Bit 15,

- Multiturn Bit 16 ... Bit 21, Status Bit 22 ... Bit 24 Zero point, sync./async. operating mode
 - adjustable via Easy Teach
- Compatible with all standard SSI masters
 In sync. mode, jitter < 5 µs required on the master side
- Immune to electromagnetic interference
 15...30 VDC
- Male M12 x 1, 8-pin

Wiring diagram



Technical data

Communication protocol	SSi		
Output function	8-pin, 25 Bit, Gray coded		
Process data area	configurable		
Diagnostic bits	Bit 22: Position was changed during power drop Bit 23: Positioning element has reached the end of the measuring range. This is indicated by a lower signal quality. Bit 24: Positioning element is outside the measuring range.		
DeviceNet input data	Data messages parametrizable as multiturn and singleturn process data or error bits		
Sample rate	5000 Hz		
	The sensor's sampling rate depends on the master's SSI cycle time. Sampling rate 15 KHz in synchronized operating mode (signal propagation delay 200 µs)		
Current consumption	< 100 mA		
Mechanical data			
Design	QR24		
Dimensions	81 x 78 x 24 mm		
Flange type	Flange without mounting element		
Shaft Type	Hollow shaft		
Shaft diameter D (mm)	6 6.35 9.525 10 12 12.7 14 15.875 19.05 20		
Housing material	Metal/plastic, ZnAlCu1/PBT-GF30-V0		
Electrical connection	Connector, M12 × 1		
Environmental conditions			
Ambient temperature	-25+85 °C		
	Acc. to UL approval to +70 °C		
Vibration resistance	55 Hz (1 mm)		
Vibration resistance (EN 60068-2-6)	20 g; 103000 Hz; 50 cycles; 3 axes		
Shock resistance (EN 60068-2-27)	100 g; 11 ms ½ sine; 3 × each; 3 axes		
Continuous shock resistance (EN 60068-2-29)	40 g; 6 ms ½ sine; 4000 × each; 3 axes		
Protection class	IP68 IP69K		





Functional principle

The measuring principle of inductive encoders is based on oscillation circuit coupling between the positioning element and the sensor, whereby an output signal is provided proportional to the angle of the positioning element. Turck refers to semi-multiturn because the multiturn process data is calculated internally from the number of single-turn zero passes. Because the sensor does not detect any revolutions when not supplied with power, the plausibility of the multiturn process data is indicated by a diagnostic bit. The rugged sensors are maintenanceand wear-free thanks to the contactless operating principle. They convince through their excellent repeatability, resolution and linearity within a broad temperature range. The innovative technology ensures high immunity to electromagnetic DC and AC fields.



Technical data

MTTF	138 years acc. to SN 29500 (Ed. 99) 40 °C
Power-on indication	LED, Green
Measuring range display	LED, yellow, yellow flashing
Error indication	LED, red
Included in delivery	MT-QR24 mounting aid
UL certificate	E210608



Mounting instructions



Extensive range of mounting accessories for easy adaptation to many different shaft diameters. Based on the functional principle of RLC coupling, the encoder is immune to magnetized metal splinters and other interferences.

The adjacent figure shows the two separate units, sensor and positioning element. Mounting option A:

First, interconnect positioning element and rotatable shaft with the bracket. Then place the encoder above the rotating part in such a way that you get a tight and protected unit. Mounting option B:

Push the encoder on the back site of the shaft and fasten it to the machine. Then clamp the positioning element to the shaft with the bracket.

Mounting option C:

If the positioning element is screwed on a rotating machine part and not to a shaft, you must first put on the dummy plug RA8-QR24. Then tie up the bracket. Screw on the encoder via the three bores.

When mounting, ensure that the positioning element is correctly aligned towards the sensor's active face. For correct fitting see arrow on the edge of the positioning element. (Arrow must point in direction of sensor)

Due to the separate installation of positioning element and sensor no electrical currents or harmful mechanical forces are transmitted via the shaft to the sensor. The encoder also offers a high degree of protection for life and stays

a high degree of protection for life and stays permanently sealed. The accessories enclosed in the delivery help to mount encoder and positioning element at an optimal distance from each other. LEDs indicate the switching status. Optionally, you can use the shield plates which are included in the accessories to increase the allowed distance between positioning element and sensor. Status display via LED green Sensor is supplied correctly, asynchronous mode green flashing Sensor is supplied properly, synchronous mode green fast flashing: Sensor is supplied properly but is not receiving CLK pulses from the SSI master yellow Positioning element is in the measuring range, signal low (e.g. distance too large), see status bit 23 yellow flashing Positioning element is outside the coverage, see status bit 24 off Positioning element is in the measuring range Multiturn error

Multiturn error

changes reserved



red: Position was changed during power drop, see status bit 22

Parameters	Easy-Teach Input	LED Display	Description
Zero point	Bridge Pin 1 (GND) and Pin 8 for 2 s	Status LED flashes, after 2 s steady	Encoder position set to zero. The Multiturn flag and the red LED are reset
Switching between sync/async mode	Bridge Pin 2 (U _B) and Pin 8 for 2 s	Status LED flashes, after 2 s steady	The encoder is by default set to asynchronous mode. The encoder
		Power LED steady green: async mode, Power LED flashes green: sync mode	switches between async/ sync mode by means of a teach pulse
Effective mode	Bridge Pin 2 (U _s) and Pin 8 for 10 s	After 10 s status LED flashes for 2 s	Effective direction of encoder CW (factory setting) Multiturn values are reset
	Bridge Pin 1 (GND) and Pin 8 for 10 s	After 10 s status LED flashes for 2 s	Effective direction of encoder CCW Multiturn values are reset
Multiturn error- flag	Bridge Pin 1 (GND) and Pin 8 for 15 s	After 15 s power and status LED alterante	Multiturn Error and multiturn counters are reset
Switching between single/multiturn mode	Bridge Pin 2 (U _B) and Pin 8 for 20 s	After 20 s the red LED flashes	Validity depends on revision status
Easy-Teach reset	Bridge Pin 2 (U _B) and Pin 8 for 15 s	After 15 seconds, power and status LED flash alternately; In case the red LED lights up, the Easy-Teach reset must be triggered again	The following factory defaults are restored: Effective direction (CW), zero point, multiturn error (delete), multiturn counter (zero)

To avoid unintended teaching, keep pin 8 potential-free.

Accessories

P1-RI-QR24		1590921	P2-RI-QR24		1590922
913 10,10 10,1	10 32.5mm	Positioning element, for Ø 20 mm shafts	91 100 1110 1110 1110 1110 1110 1110 11	10 [2:59] \$25mm	Positioning element, for Ø 14 mm shafts
P3-RI-QR24		1590923	P4-RI-QR24		1590924
913 10,110 10,110 10,110 10,107 1	10 (32.59) \$2.5mm	Positioning element, for Ø 12 mm shafts	910 100 100 100 100 100 100 100 100 100	10 [2.39] @25mm	Positioning element, for Ø 10 mm shafts
P5-RI-QR24		1590925	P6-RI-QR24		1590926
92 100 100 100 100 100 100 100 10	10 13.30) \$2.5 mm	Positioning element, for Ø 6 mm shafts	analise	10 (3.39) @2.5 mm	Positioning element, for Ø 3/8" shafts



P7-RI-QR24	1590927	P9-RI-QR24	1593012
940 (1.0) (1	Positioning element, for Ø 1/4" shafts	010 010 010 010 010 010 010 010	Positioning element for installation on Ø 1/2" shafts
P10-RI-QR24	1593013	P11-RI-QR24	1593014
93 (10) (10) (10) (10) (10) (10) (10) (10)	Positioning element for installation on Ø 5/8" shafts	00 01 01 01 01 01 01 01 01 01	Positioning element for installation on Ø 3/4" shafts
P8-RI-QR24	1590916	M1-QR24	1590920
933 100 100 100 100 100 100 100 1	Positioning element with blanking plug for large shafts	010 010 010 010 010 010 010 010 010 010	Aluminum protecting ring, for inductive encoders RI-QR24
PE1-QR24	1590937	RA1-QR24	1590928
0,530 (0,13) (0	Positioning element without adapter sleeve	978 1.10 0	Adapter sleeve, for Ø 20 mm shafts
RA2-QR24	1590929	RA3-QR24	1590930
93 (1.10)	Adapter sleeve, for Ø 14 mm shafts	0.23 0.10 0.11 0.14	Adapter sleeve, for Ø 12 mm shafts
RA4-QR24	1590931	RA5-QR24	1590932
010 010 010 010 010 010 010 010	Adapter sleeve, for Ø 10 mm shafts	023 1.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	Adapter sleeve, for Ø 6 mm shafts
RA6-QR24	1590933	RA7-QR24	1590934
035 1.10 0.07 0.000 0.00	Adapter sleeve, for Ø 3/8" shafts	923 110 00r 100 000 000 000 000 000 000 000	Adapter sleeve, for Ø 1/4" shafts
RA9-QR24	1590960	RA10-QR24	1590961
	Adapter sleeve, for Ø 1/2" shafts		Adapter sleeve, for Ø 5/8" shafts
RA11-QR24	1590962	RA8-QR24	1590959
	Adapter sleeve, for Ø 3/4" shafts		Plug for mounting option C
0.10 0.00 0.00		**************************************	





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